Introduction to Large Language Models

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Goals of this short course

- Main goal: understanding the fundamentals of (large) language models
- \rightarrow The language modeling objective
- \rightarrow Sequences and the encoder-decoder architecture
- \rightarrow Attention
- \rightarrow Transformer models

Language modelling

It's about sequences

- "This morning I took the dog for a walk."
- Multimenter and the second and the sec



sentence

medical signals

speech waveform

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This morning I took the dog for a walk



Approach 1: fixed window (n-grams)

 Model the sequence in terms of smaller sub-sequences of length n (e.g. n=1, 2 or 3)

• Unigram (1-gram):
$$p(x_1, ..., x_n) \approx \prod_{i=1}^n p(x_i)$$

• Bigram:
$$p(x_n|x_1, ..., x_{n-1}) \approx p(x_n|x_{n-1})$$

Would a bigram model handle this? $p(x_n|x_1,...,x_{n-1}) \approx p(x_n|x_{n-1})$

This morning I took the dog for a..... walk



But surely, predicting *walk/vet* also depends on *dog*? With a simple Markov model like this, we cannot model long-term dependencies.

Long-distance dependencies

Word probabilities:

In Spain, I ate a lot of paella and learnt some Spanish.

Pronouns and their antecedents:

John told me he was leaving on the 24th.

Mary told me she was leaving on the 24th.

Bag of words?

- Idea: treat the whole sequence as a multiset ("bag"), where each element is represented by a count.
 - We can also weight such counts in various ways, e.g. TF/IDF

This morning <mark>I</mark> took the <mark>dog</mark> for a

- But BoW doesn't preserve order. These two are equivalent:
 - In Spain, I ate a lot of paella and learnt some Spanish.
 - I ate some paella and learnt a lot of Spanish in Spain.

Suppose we use a really big fixed-window?

- More or less, like using n-grams with larger values for n
 - E.g. consider previous 5 words

This morning I took the dog to thevet

Long-distance dependencies (again)

Word probabilities:

In Spain, I ate a lot of paella and learnt some Spanish.

Pronouns: John told me he was leaving on the 24th. Mary told me she was leaving on the 24th.

Distance is not fixed:

John, who is my mother's brother, told me <mark>he</mark> was leaving on the 24th. Mary, who is my father's sister, told me <mark>she</mark> was leaving on the 24th.

Summary: The challenges of sequences

Ideally, we want to deal with:

- variable length
- order preservation
- long-distance dependencies
- parameter sharing across the sequence

Recurrent networks

Recurrent Neural Networks (RNNs)

- Rationale:
 - Rather than fixing the amount of history our network can handle, we allow it to **accumulate a representation over time**.
 - This can work over arbitrary sequences.
 - Hopefully, it will also encode similar things in similar ways (less representational redundancy).
 - In the accumulated representation, it should also capture dependencies between elements at different (possibly distant) time-steps.

Recurrent Neural Network



Recurrent Neural Network



RNN maintains a hidden state across timesteps which accumulates the sequence representation.

Unrolled RNN



- Processes a sequence $x_1, ..., x_t$ via hidden units $h_1, ..., h_t$ to yield an output sequence.
 - Key property: share parameter matrices U, W and V across time.

Recurrent neural network: parameters



Recurrence formula

Often, g = tanh

$$\begin{aligned} h_t &= f\left(h_{t-1}, x_t\right) = g\left(Wh_{t-1} + Ux_t\right) \\ y_t &= Vh_t \end{aligned} \text{Previous hidden state Input Shared W}$$

Input vector at current timestep. Shared U

Recurrent Neural Networks: Process Sequences



Depth



RNN with two layers.

- We can stack multiple hidden layers in the RNN and connect them.
- Each layer has its own weight matrix for hidden states (W) and inputs (U) are:

$$h_t^l = g\left(W^l h_{t-1}^l + U^l h_t^{l-1}\right) \lim_{\text{previous layer (= x at layer 1)}} \|h_t^{l-1}\|_{\text{previous layer 1}} \|h_t^{l-1}\|_{\text{previous layer 1}} \|h_t^{l-1}\|_{\text{previous layer 1)}} \|h_t^{l-1}\|_{\text{previous layer 1}} \|h_t^{l-1}\|_{\text{previous layer 1}}$$

Bidirectionality



 $\begin{array}{rcl} h_t &=& g\left(Wh_{t-1} + U_t^x\right) \\ \overline{h}_t &=& g\left(\overline{Wh}_{t+1} + U_t^x\right) \\ y_t &=& V\left[h_t; \overline{h}_t\right]^T \end{array}$

Gating (brief outline)

RNNs can handle arbitrary sequences, but they do forget!

• During training, long-distance dependencies are "lost" as the impact of early elements is diminished over time.

Gated Recurrent Unit (GRU)

Long Short-term Memory (LSTM) network

• Two variations of RNNs use "gates" to allow the network to selectively retain or "forget" information.

Training with cross-entropy loss



Prediction with a trained RNN



Encoder-Decoder Architecture

Causal ("auto-regressive") generation

• Basic idea: condition next word prediction on the preceding word, plus the hidden state.



Causal ("auto-regressive") generation

- At each time step *t*, sample from the vocabulary V, and choose the most likely next element, based on:
 - Current hidden state (which accumulates the representation up to *t-1*)
 - Previous word generated at *t-1*
- Notice, however, that this generates random sequences.
 - What is the text being generated actually about?
- Suppose we want to generate from some input?
 - Idea: condition word choice based on the input, as well as previously generated words.

Encoder-Decoder architecture



Sutskever, I., Vinyals, O., & Le, Q. V. (2014). Sequence to sequence learning with neural networks. *Advances in Neural Information Processing Systems 27 (NIPS'14)*, 3104–3112. <u>http://papers.nips.cc/paper/5346-sequence-to-sequence-learning-with-neural</u>

Cho, K., van Merriënboer, B., Gulcehre, C., Bahdanau, D., Bougares, F., Schwenk, H., & Bengio, Y. (2014). Learning Phrase Representations using RNN Encoder–Decoder for Statistical Machine Translation. *Proceedings of the 2014 Conference on Empirical Methods in Natural Language Processing (EMNLP)*, 1724–1734. <u>https://doi.org/10.3115/v1/D14-1179</u>

Encoder-Decoder architecture



Encoder-Decoder architecture



Image and caption taken from the COCO Challenge. https://cocodataset.org/#captions-2015

Where do we factor in the context?

Various ways to do this. Here are two:

Initialise

- Initialise the decoder with the encoder's last hidden state
- During decoding, decoder predicts the next element with the previous hidden state and the predictions generated so far.

Use context at each step

- Inject the context into each time-step of the decoder
- At each timestep, decoder predicts based on its previous hidden state, predictions generated so far, and the context.

The encoder-decoder model at inference time (NB: context injected at each step)



Where does attention come into the picture?



The original E-D creates a **bottleneck**: All the input is compressed into a dense representation, which is used throughout decoding.

Attention mechanisms allow the decoder to learn to differentiate between parts of the input context. So at each time-step, we train it to pay more attention to relevant portions of the input.

Transformers are based on a generalization of the attention mechanism.

Attention in Encoder-Decoder models



Encoder

Attention in Encoder-Decoder models

- Suppose input is of length n. Then the Encoder has n states, one for each time-step (word etc): h^e₁...h^e_n
- Let c_i be the decoder context at timestep i. We want this to reflect how relevant each encoder state is to the decoder state h^d_{i-1}.
 - We capture this by comparing h_{i-1}^d to each encoder state h_i^e .

Attention in Encoder-Decoder models

1. Capture their similarity: compare the decoder state to each encoder state:

$$\operatorname{score}(h_i^d, h_j^e) = h_i^d \cdot h_j^e$$

- 2. Normalise scores using softmax (turn them into a distribution): $\alpha_{ij} = \operatorname{softmax}(\operatorname{score}(h_i^d, h_j^e), \forall j \in e)$
- 3. Use that distribution to compute a weighted average over all the hidden encoder states:

$$c_i = \sum_j \alpha_{ij} h_j^e$$

What does this do?

 Hopefully, during training, we achieve a way to identify, at each timestep in the decoder, which part of the source encoding is most relevant.



Attention as "alignment"





A stop sign is on a road with a mountain in the background,



A woman holding a clock in her hand.

Bahdanau, D., Cho, K., & Bengio, Y. (2015). Neural Machine Translation By Jointly Learning To Align and Translate. *Proceedings of the International Conference on Learning Representations (ICLR'15)*, 1–15. https://doi.org/10.1146/annurev.neuro.26.041002.131047 Xu, K., Ba, J. L., Kiros, R., Cho, K., Courville, A., Salakhutdinov, R., Zemel, R. S., & Bengio, Y. (2015). Show, Attend and Tell: Neural Image Caption Generation with Visual Attention. *Proceedings of the International Conference on Learning Representations (ICLR'15)*. http://arxiv.org/abs/1502.03044

Summary for today

- Language modelling objective
 - Basically, word prediction given a preceding context.
- Recurrent networks
 - Architecture to handle sequences of arbitrary length.
- Endoder-Decoder
 - Architecture (originally with RNNs) to drive a language model to generate, conditioned on input context.
- Attention
 - Key step to condition the LM selectively on different parts of the input, at each timestep.

What's next?

- The current generation of "large language models" is based on Transformer architectures.
- These generalise the notion of attention, while removing recurrence completely.
- Next time:
 - Generalisation of attention
 - Transformers and self-attention
 - Concrete examples of transformer-based LMs.